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W. A. Crosby Calspan Field Services, Inc.

November 1981

Final Report for Period 27 October 1981

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AIR FORCE SYSTEMS COMMAND
UNITED STATES AIR FORCE

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FOR THE COMMANDER

JOHN M. RAMPY, Director

Aerospace Flight Dynamics Test

Deputy for Operations

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NOMENCLATURE

Α Cavity acoustic data-type ALPHAC Cavity model angle of attack or CTS pitch drive, deg ALPHAP Probe angle of attack, deg CODE Model configuration number Model configuration designation CONFIG Pitch plane cone probe differential pressure, DPP PCS1-PCS3, psia DPY Yaw plane cone probe differential pressure, PCS2-PCS4, psia **ETAC** CTS aft yaw drive, deg FE.ICE Suppression fence height in percent of estimated boundary layer thickness ($\delta = 0.468$ in.) GRID A predetermined set of probe positions used to command the CTS motion in computer control M Free-stream Mach number MC Computed cone probe Mach number MP Computed rearward-facing pitot probe Mach number P Free-stream static pressure, psia or probe data-type **PCSi** Cone probe static pressures, i=1-4, psia Accession For NTIS Average cone probe static pressure, psia **PCSA** Dric Tab Unanuconsed PCT Cone probe total pressure, psia

DTIC COP**Y** NSPE**CTE**E

CTS roll drive, deg

PHICB

PHIP Probe roll angle, deg

PN Data point number

PPT Rearward-facing probe total pressure, psia

PT2 Stagnation pressure downstream of a normal shock,

psia

PT Tunnel stilling chamber pressure, psia

PW Cavity static pressure data-type

Q Free-stream dynamic pressure, psia

RE Free-stream unit Reynolds number, ft-1

RUN Data set identification number

STORE Percent of cavity cross section area

occupied by store shape (total area = 36 in.²)

T Free-stream static temperature, °R

Txxx Cavity static pressure tap number

TxxxA Cavity acoustic pressure tap number

TPT Total temperature probe temperature, °R

TRIP Boundary layer trip size, in.

TT Tunnel stilling chamber temperature, °R

X Axial drive position, in.

XC CTS axial drive, in.

XO Cavity model axial coordinate, positive aft from

model leading edge, in.

XPC, XPP, XPT Axial position of cone, pitot, and temperature

probes, respectively, from cavity model leading

edge, in.

Y	Lateral drive position, in.
YAWC	Cavity model yaw angle or CTS forward yaw drive, deg
YAWP	Probe yaw angle, deg
Y 0	Cavity model lateral coordinate, positive right (looking upstream) from model centerline, in.
YPC,YPP,YPT	Lateral position of cone, pitot, and temperature probe, respectively, from cavity model centerline, in.
z	Vertical drive position, in.
zc	CTS vertical drive, in.
20	Cavity model vertical coordinate, positive up from the top of cavity, in.
ZPC,ZPP,ZPT	Vertical position of cone, pitot, and temperature probes, respectively, from the top of the cavity, in.
δ	Theoretically estimated turbulent boundary layer thickness, in.

1.0 INTRODUCTION

The work reported herein was performed by the Arnold Engineering Development Center (AEDC), Air Force Systems Command (AFSC), under Program Element 61101F, Control Number 0100, at the request of Air Force Weapons Laboratory (AFWL), Kirtland Air Force Base, New Mexico 87117. The AFWL/NTSAC project manager was Mr. J. W. Doran. The results were obtained by Calspan Field Services, Inc./AEDC Division, operating contractor for the Aerospace Flight Dynamics testing effort at the AEDC, AFSC, Arnold Air Force Station, Tennessee. The test was performed in the von Karman Gas Dynamics Facility (VKF) Supersonic Tunnel A on 27 October 1981, under AEDC Project number C146VA.

The test objective was to provide experimental data to support verification of Lockheed General Interpolants Method (GIM) computer code for two-dimensional flow in a simulated weapons cavity.

Testing was accomplished at Mach 3, Reynolds number 3.0×10^6 ft⁻¹ at zero incidence to the free-stream. Vertical flow-field surveys were made forward, aft, and within the cavity utilizing a probe mounted on the VKF Captive Trajectory System (CTS). The instrumented cavity length-to-depth ratio was 2.25. Data were obtained on configurations of varying store sizes (relative to cavity cross section area) and suppression fence height. Photographic data were obtained at all test data points. Expected cavity wave motion was not detectable either acoustically or optically during the test. However, a subsequent review of the high speed schlieren (4000 fps) movies obtained indicates that a typical cavity wave motion was present.

All test data have been transmitted to the sponsor/user as described in Table 1. Inquiries to obtain copies of the test data should be directed to AFWL/NTSAC, Kirtland Air Force Base, NM 87117. A microfilm record of the tabulated data has been retained in the VKF at AEDC.

2.0 APPARATUS

2.1 TEST FACILITY

Tunnel A (Fig. 1) is a continuous, closed-circuit, variable density wind tunnel with an automatically driven flexible-plate-type nozzle and a 40- by 40-in. test section. The tunnel can be operated at Mach numbers from 1.5 to 6 at maximum stagnation pressures from 29 to 200 psia, respectively, and stagnation temperatures up to 750°R at Mach number 6. Minimum operating pressures range from about one-tenth to one-twentieth of the maximum at each Mach number. The tunnel is equipped with a model injection system which allows removal of the model from the test section while the tunnel remains in operation. A description of the tunnel and airflow calibration information may be found in the Test Facilities Handbook*.

Test Facilities Handbook (Eleventh Edition). "von Karman Gas Dynamics Facility Vol. 3" Arnold Engineering Development Center, June 1979.

2.2 TEST ARTICLE

The test article (Fig. 2) was a simulated weapons cavity of length-to-depth ratio 2.25 cut out from a flat-top wedge designed and fabricated at AEDC. The stainless steel model was instrumented with 40 static pressure orifices and five acoustic microphones (Table 2). The static pressure orifices were arranged in 5 rays to obtain cross flow pressure distribution. The cavity was located 30.0 in. from the flat plate leading edge. The rear wall was situated 9.0 in. downstream of the cavity edge. A boundary layer trip consisting of a Carborundum 5 grit (#60, 0.0160 in. height) strip 0.25 in. wide was located 1.5 in. from the leading edge to induce transition of the boundary layer. Model configuration variables included suppression fences and simple store shapes. Interchangeable fences (Fig. 2d) of 0.0, 0.5, and 1.0 boundary layer thickness were provided (boundary layer thickness, &, was estimated as 0.47 in.). The 0.5 δ fence was not used. Simplified store shapes (Fig. 3) with pylon attachments were built corresponding to 25, 50, and 75 percent of the total cavity cross-section area (36.0 in. 2). The 75 percent store was not used. The baseline configuration was the empty cavity without the fence.

Flow field surveys were made using the probes shown in Fig. 4. The probes mounted on the CTS consisted of a 5-hole Mach number/flow angularity 20 deg half-angle cone probe, an unshielded Chromel®-Alumel® total temperature probe, and a 0.093 in. OD rearward facing Mach number pitot probe. Details of the cone probe are provided in Fig. 5.

An installation sketch of the model in Tunnel A is provided in Fig. 6, and an installation photograph is shown in Fig. 7.

2.3 TEST INSTRUMENTATION

The cavity model was instrumented with 40 surface static pressure taps longitudinally spaced in 0.5 in. (or greater) increments on five lateral rays. The lateral rays were required to check for three dimensional flow effects. The primary instrumentation ray was along the model centerline. In addition, five dynamic pressure transducers were located in the cavity model and used to record acoustic environment and average cavity sound pressure level. Model angle of attack was set to zero as indicated by an on-board inclinometer.

The flow field probe (details provided in Section 2.2) was mounted on the VKF Captive Trajectory System (CTS). The CTS* consists of a model support with electro-mechanical drive systems for six degrees of freedom and is attached to the top of the tunnel as shown in the conceptual drawing given in Fig. 8. The axial and vertical motions (XC and ZC) are obtained using linear drive units while lateral motion is achieved by rotating the roll-pitch-yaw support arm about the vertical support axis with the aft yaw mechanism (ETAC) and compensating for the resulting yaw with the forward yaw mechanism (YAWC). The forward yaw

Billingsley, J. P., Burt, R. H., and Best, J. T. "Store Separation Testing Techniques at the Arnold Engineering Development Center, Volume III: Description and Validation of Captive Trajectory Store Separation Testing in the von Karman Facility." AEDC-TR-79-1, March 1979.

and pitch (ALPHAC) motions are obtained through two knuckle joints with axes 90 deg to each other (the pitch axis is upstream of the yaw axis), and finally the most upstream motion of the system is the roll (PHICB). Only the axial, vertical, and pitch motions were required to achieve the test objectives. The excursion bands and rates of travel of the CTS drives are given in Table 3. The measuring devices, recording devices, calibration methods, and estimated measurement uncertainties of the six degree of freedom motions of the CTS are given in Table 4.

The measuring devices, recording devices, and calibration methods used for all other measured parameters are also listed in Table 4 along with their estimated measurement uncertainties.

Model flow-field photographs were obtained using the VKF Tunnel A double-pass optical flow visualization system. Color schlieren 70mm stills were made using this system at all test data points. High speed (4000 fps) 16 mm color schlieren movies were obtained on each configuration without the influence of the probe. A video cassette recording of the entire test was also made with this system.

3.0 TEST DESCRIPTION

3.1 TEST CONDITIONS

A summary of the nominal test conditions is given below.

<u>M</u>	PT, psia	TT, °R	Q, psia	P, psia	$RE \times 10^{-6}/ft$
3.0	18.8	530 ·	3.201	0.505	3.0

At some test conditions, particularly at sub-atmospheric stagnation pressures, the air humidity level affects the test section Mach number. The Tunnel A sidewall Mach number probe is used periodically when testing at these conditions to monitor deviations from the standard calibrated Mach numbers. When a deviation is measured, the freestream conditions are corrected and the actual Mach number is printed on the data tabulations.

A test summary showing all configurations tested and the variables for each is presented in Table 5.

3.2 TEST PROCEDURES

3.2.1 General

For CTS tests in the VKF continuous flow wind tunnels (A, B, C), the parent (cavity) model is mounted on a sting support mechanism in an installation tank directly underneath the tunnel test section. The tank is separated from the tunnel by a pair of fairing doors and a safety door.

When closed, the fairing doors, except for a slot for the pitch sector, cover the opening to the tank and the safety door seals the tunnel from the tank area. After the parent model is prepared for a data run, the personnel access door to the installation tank is closed, the tank is vented to the tunnel flow, the safety and fairing doors are opened, the model is injected into the airstream, and the fairing doors are closed. The parent model was leveled to zero angle of attack and the data obtained. After this, the sequence is reversed and the tank is vented to atmosphere to allow access to the model in preparation for the next data set. The sequence is repeated for each configuration change. Flow field probe attitude and positioning and data recording were accomplished using the CTS in the grid mode of operation. The grid matrices, which are tables of model attitude and position, were loaded into the VKF DEC 10 computer prior to the test. During the test, the required grid was selected and the positioning of the model was controlled by the computer which automatically recorded all the data inputs at each grid point location. Grid survey stations are shown in Fig. 9. Vertical probe surveys were accomplished by driving the CTS in 0.250 in. increments when inside the cavity and in 0.125 in. increments when the probe centerline was at or above ZO = 0.00 in. Probe centerline was typically 0.250 in. (0.336 in. for 50 percent store) above the model or store surface at the initiation of the survey. All vertical surveys were terminated 1.125 in. above the top of the cavity. The process was repeated until the grid matrix was completed. The data recording for the cavity model was accomplished using the tunnel data acquisition system which was also automatically controlled by the computer.

Initial alignment of the probe and cavity model was achieved through a "touch" docking technique utilizing the CTS electrical grounding circuit. Once the cavity model was leveled the probe was moved to precision wind-off alignment positions. Axial location was checked optically with a scope and the probe driven vertically downward until contact was made with the cavity model, thus completing the ground loop circuit and stopping all drives. The probe was then raised 0.100 in. from the model surface using known linear drive potentiometer settings. Air-on docking positions were recorded such that subsequent dockings were repeated precisely.

3.2.2 Data Acquisition

As described in Section 3.2.1, data were taken in the grid mode of operation using the CTS and tunnel data systems. Data were obtained at predetermined values of probe positions. Dynamic pressure measurements in the cavity (without probe interference) were recorded on analog tape over a time period of 30 sec. Pressure data and probe position data utilized 1 and 10 samples, respectively, taken over a 1 sec time span.

3.3 DATA REDUCTION

Cavity model and probe pressure/temperature data were obtained utilizing the CTS data acquisition system as described in Section 3.2. Cavity surface static pressure data were normalized by free-stream static pressure. Cavity acoustic environment was converted to sound pressure level. Probe parameters were true readings. Cone probe differential pressures were also provided.

Cone-derived Mach number (MC) was evaluated by a technique developed at VKF for this probe and is described in AEDC-TR-80-52*. Rearward facing pitot probe Mach number was evaluated but was nominally zero.

Relative probe positions were given in inches referenced to the centerline point on the cavity model leading edge (Fig. 9).

3.4 UNCERTAINTY OF MEASUREMENTS

In general, instrumentation calibrations and data uncertainty estimates were made using methods recognized by the National Bureau of Standards (NBS)**. Measurement uncertainty is a combination of bias and precision errors defined as:

$$U = \pm (B + t_{95}S)$$

where B is the bias limit, S is the sample standard deviation, and t_{95} is the 95th percentile point for the two-tailed Student's "t" distribution (95-percent confidence interval), which for sample sizes greater than 30 is taken equal to 2.

Estimates of the data uncertainties in the basic measurements of this test are given in Table 4a. Data uncertainties are determined from in-place calibrations through the data recording system and data reduction program.

Propagation of the bias and precision errors of measured data through the calculated data are made in accordance with the reference** below and the results are given in Table 4b.

4.0 DATA PACKAGE PRESENTATION

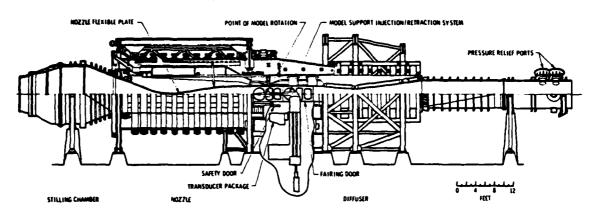
The data package contains tabulated cavity model and probe pressure data along with tunnel condition and position data. Sample tabulations are given in Appendix III.

Gray, J. D. and Billingsley, J. P. "Internal Drag Experiments for Data Correlation, ASALM PTV/TVV," AEDC-TR-80-52, May 1981.

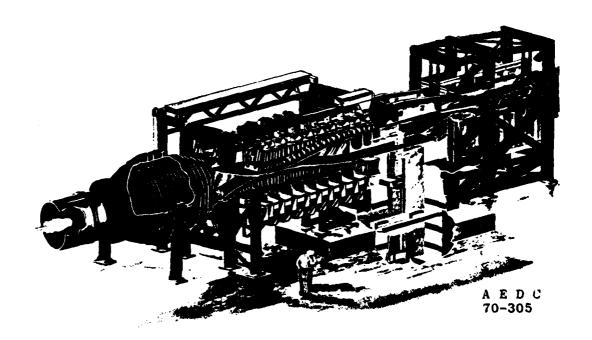
^{**} Thompson, J. W. and Abernethy, R. B. et al., "Handbook Uncertainty in Gas Turbine Measurements." AEDC-TR-73-5 (AD755356), February 1973.

APPENDIX I

ILLUSTRATIONS



a. Tunnel assembly



b. Tunnel test section Fig. 1 Tunnel A

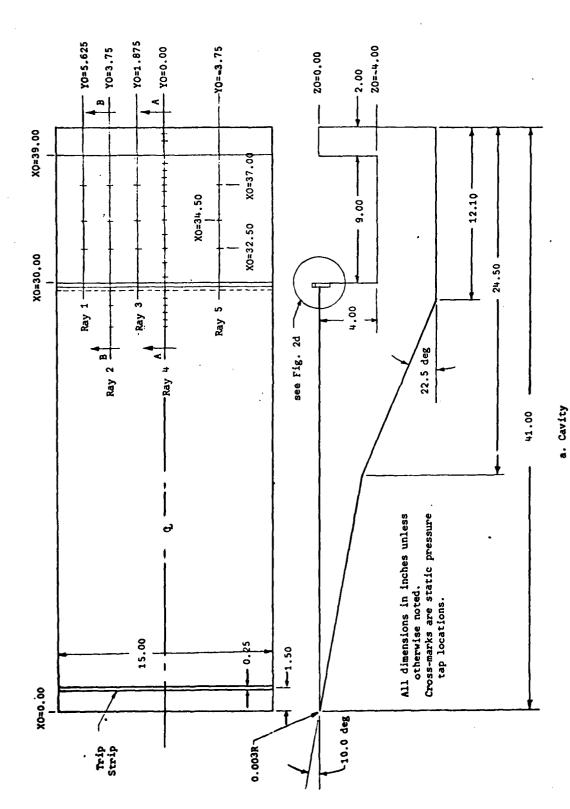
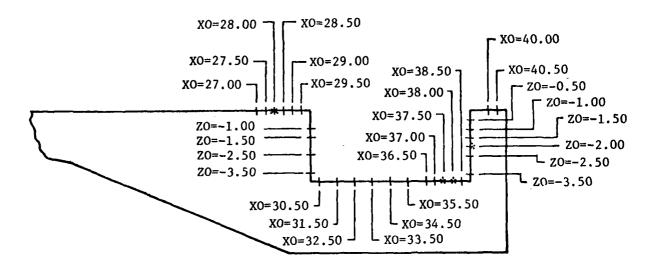
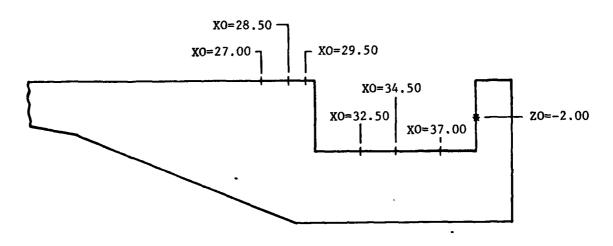


Figure 2. Cavity Model Details



View A-A
b. Ray 4 Detail (Y0=0.00)

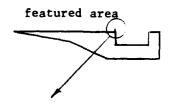


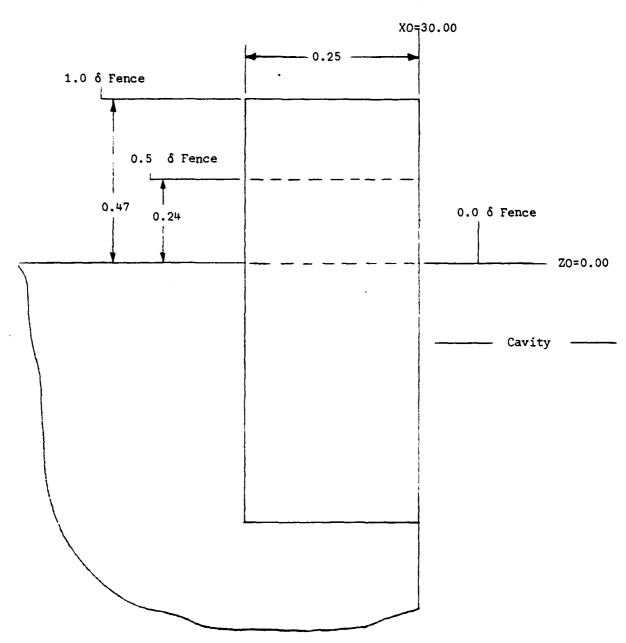
View B-B
c. Ray 2 Detail (Y0=3.75)

Cross-marks are static pressure tap locations.
"*" denotes dynamic pressure transducer.
Rays 1, 3, 5 detail given on Fig. 2a.

Figure 2. Continued

Fences extend full span of cavity (15.00in.). δ = Estimated turbulent boundary layer height.





d. Enlarged View of Suppression Fence

Figure 2. Concluded

All dimensions in inches unless otherwise noted. Store sizes relative to 36in.² cavity cross-section area. Store shapes are full span of cavity (15.00 in.).

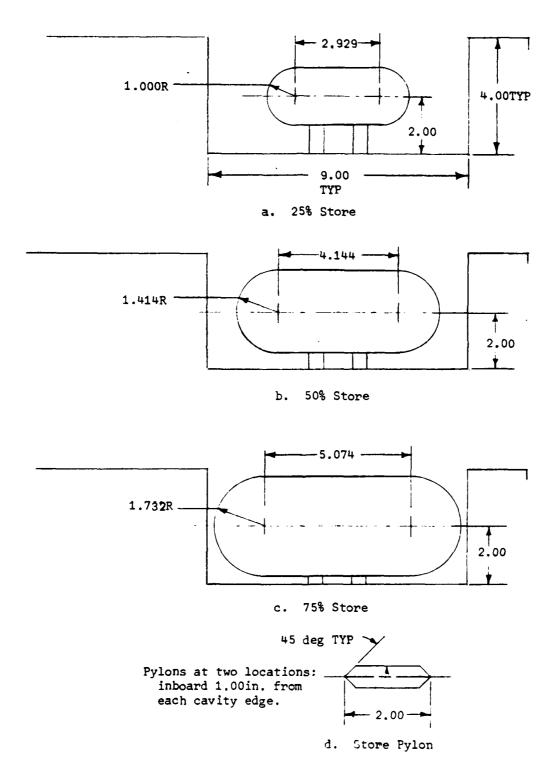


Figure 3. Cavity Store Shapes with Pylon

All dimensions in inches unless othewise noted.

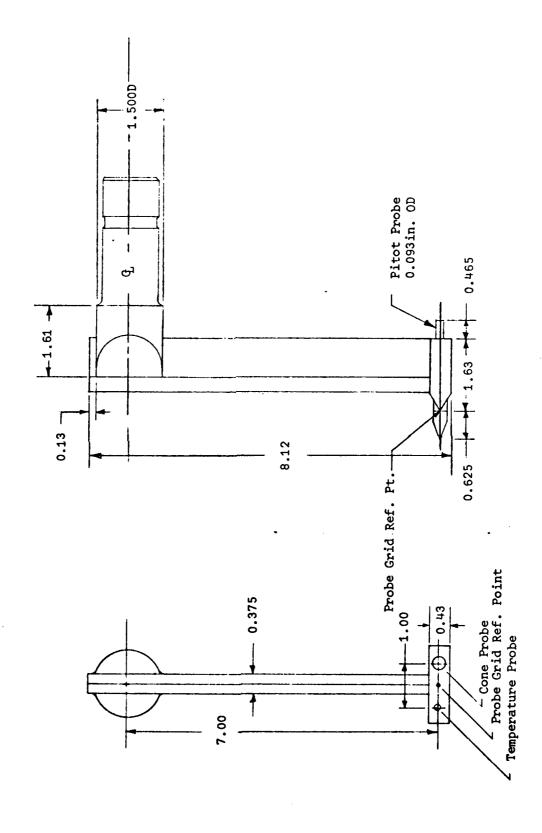
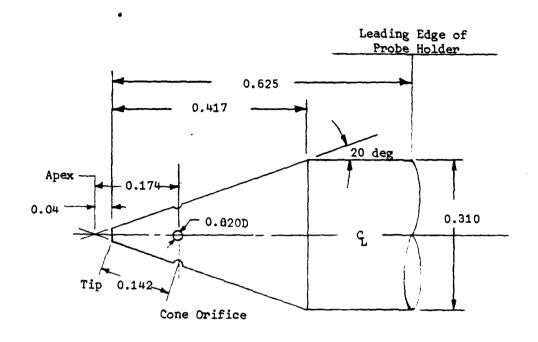


Figure 4. Probe Holder Details



All dimensions in inches unless otherwise noted.

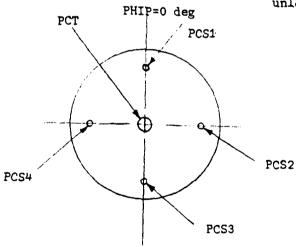


Figure 5. Details of Cone Probe

View Looking Downstream

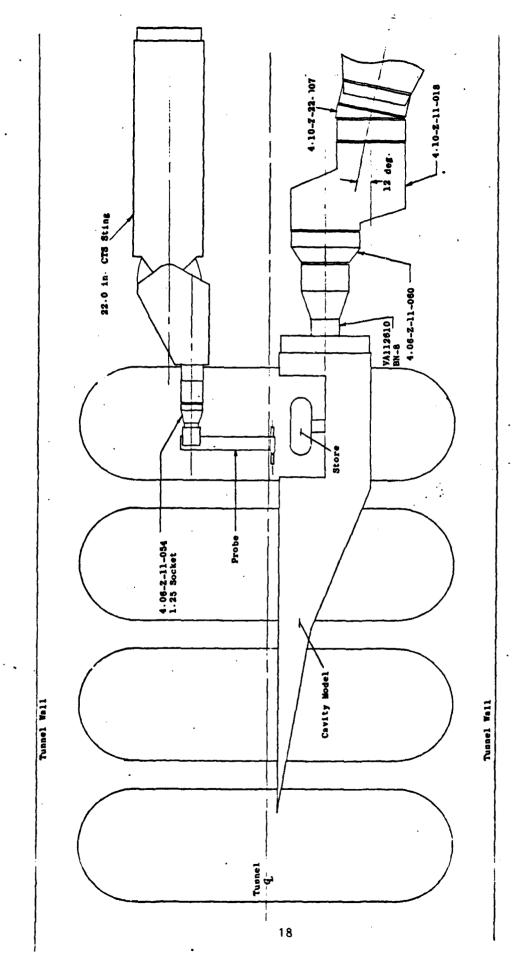
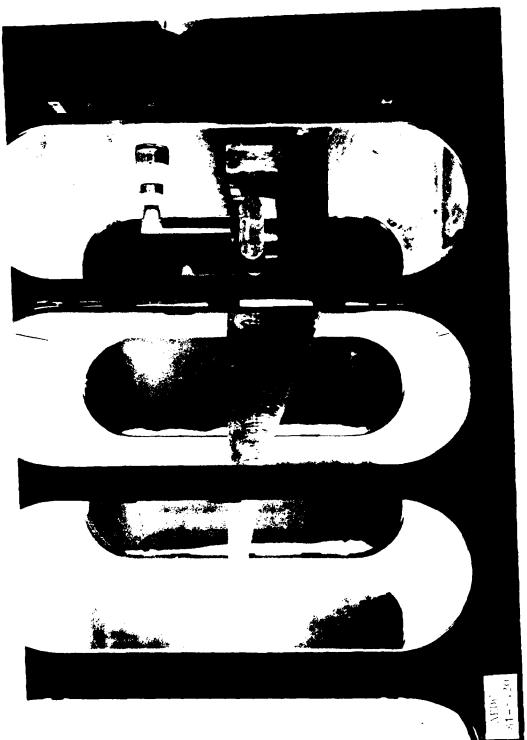


Figure 6. Installation Sketch



The second secon

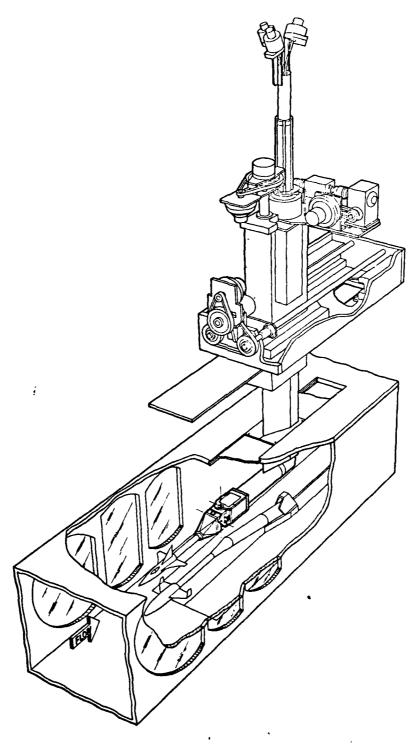
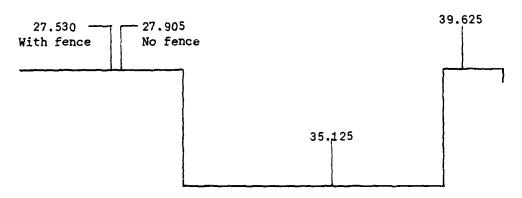


Figure 8. Artist's Conception of the VKF/CTS Installed in Tunnel A



Actual probe tip locations are given by the following since orientations (ALPHAP, YAWP, PHIP) are zero or negligible.

Cone Probe	Pitot Probe	Temperature Probe
XPC = X-0.625	XPP = X+2.095	XPT = X-0.625
YPC = Y-0.500	YPP = Y-0.500	YPT = Y+0.500
ZPC = Z	ZPP = Z	ZPP = Z

All survey stations have probe grid reference point on model centerline, Y0 = 0.00. Axial locations are for probe grid reference point from leading edge of flat plate, X0 = 0.00. Probe grid reference point shown in Figure 4.

Figure 9. Grid Survey Stations

APPENDIX II

TABLES

TABLE 1. Data Transmittal Summary

The following items were transmitted to the Sponsor/User.

Sponsor/User

Mr. J. W. Doran AFWL/NTSAC Kirtland AFB, NM 87117

Item	No.	of	Copies
Final Tabulated Data, Runs 1-20*,+		2	(Others: 1 copy)
Data Transit Tape+		1	
Sample Tape Printout+		1	
Data Transit Tape Format+		1	
70mm Schlieren Stills* Roll No. 0052		1 1	Contact Print Duplicate Negative
16mm Schlieren Movies: Reel Nos. 4548-4553		1	Optical Master Work Print*
Photographic Data Log		1	
Video Cassette, Runs 1-20		1	
Model Installation Photographs, 8x10 prints*,+		2	(Others: 1 copy)

Other Data Distribution:

- * Mr. L. L. Shaw AFWAL/FIBE Wright Patterson AFB, OH 45433
- + Mr. Alan Ratliff LMSC 4800 Bradford Blvd. Huntsville, AL 35807

TABLE 2. Cavity Instrumentation Summary

		i	
TXXX	хо	YO	20
101	32.50	5.625	-4.00
102	34.50	1 1	[
103	37.00	1	4
201	27.00	3.75	0.00
202	38.50	li	
203	29.50	l . l	
204	32.50		-4.00
205	34.50		į
206	37.00		•
207A	39.00	4	-2.00
301	32.50	1.875	-4.00
302	34.50		
303	37.00	♦	*
401	27.00	0.00	0.00
402	27.50	l i l	
403A	28.00		
404	28.50		
405	29.00		
406	29.50		▼
407	30.00		-1.00
408			-1.50
409			-2.50
410	†	₩	-3.50

Txxx	хо	YO	ZO
411	30.50	0.00	-4.00
412	31.50		
413	32.50		1
414	33.50		
415	34.50	'	
416	35.50	}	} }
417	36.50	1	
418	37.00		
419A	37.50		
420A	38.00		
421	38.50		1
422	39.00		-3.50
423			-2.50
424A			-2.00
425			-1.50
426	!	1	~±.00
427	7		-0.50
429	40.00		0.00
£30	40.50	†	0.00
501	32.50	-3.75	-4.00
502	34.50		
503	37.00	+	\

TABLE 3. CTS Motion Capabilities in Tunnel A

MOTION	MAXIMUM ¹ TRAVEL LIMITS	MAXIMUM ² RATE OF TRAVEL
xc	±20 in.	1.2 insec-1
zc	±15 in.	$1.2 in sec^{-1}$
ETAC ³	±25 deg	2.7 deg-sec ⁻¹
YAWC3	±45 deg	10.4 deg-sec ⁻¹
ALPHAC	±45 deg	11.7 deg-sec ⁻¹
PHICB	±180 deg	20.5 deg-sec ⁻¹

- NOTES: 1. Travel limits are set up for each test as a function of model location in the tunnel and the test requirements.
 - 2. Rates are continuously variable up to the values shown and can be computer controlled to allow all drives to reach a commanded point simultaneously.
 - 3. YAWC and ETAC combine to provide a lateral motion of ± 15 in.

CTS Motion Nomenclature

ALPHAC	CTS pitch drive, deg
ETAC	CTS aft yaw drive, deg
PHICB	CTS roll drive, deg
xc	CTS axial drive, in.
YAWC	CTS forward yaw drive, deg
zc	CTS vertical drive, in.

TABLE 4. ESTIMATED UNCERTAINTIES
a. Basic Measurements

		STEAD	STEADY-STATE	•	ESTIMATED MEASURENENT*	EXENT					
	Precis	Precision Index ± (S)		1	Bias AB)	unce ±(B	Uncertainty ±(B + t95S)		6.2.4	i co	Xethod of
Parameter Designation	Percent 10 Rathsuff	Unit of Yeasure ment	Degree of	Joseph Jo Raithsoff	to tinU -eruzaeM tuem	Percent to Reading	To Jiny Sanstak Juom	Range	Measuring Device	Recording Device	On the control of the
PT. ps. a		0.007	30	0.5		0.2';PT +	+ 0.014	1	Bell and Howell Force Balance Pressure Transduerr	Amelog to Digital (A.D) Converter into Digital Data Acquisition System (BAS)	In-line appropriation of markets
1° E		1.0	30		2.0		0.4	70-300	Chromel"-Alumel Thermocouple	Digital scanner via New villering as a microprecessor based NNS concernity malliplexer via Flabellest-vell, constructed digital liberworseter tallier callier.	System Programmes Missing Conference Programmes Conference Confere
CTS brives		!		1			; ;			4	
XC.1n ZC.1n PHR B.deg ALPI VC.deg YV.V. de B.M. deve		0.0040 0.0056 0.0877 0.0295 0.0264	000000		0.0021 0.0004 0.0004 0.0102		0.0101 0.0116 0.1754 0.0632 0.0408	1150 1150 1150 1150 1150 1150 1150	Potentiometer	Digital geometry:a A b convertor	Properties of the Properties o
ALPHAC, deg (cavity)		0.005	90		0.05		90-0		Shaevitz Servo		Competition at the rate of the control of the contr
VAMC, deg (cavity)		0.25	30		+0		0.30	±0.5	lino-	Vanual	Fixed Person Street
TREE, ps ta		0.0015	30	0.15		0.15%Txx	0.15%Txxx + 0.0030	0-15		A D Converter into DBAS	Principal Control Cont
PUSI - PCS4, PCT, PPT, psia	:	0.003	30		0.005		0.011	0-15	Kistler Force Balance Pressure Transducer		Carolina and Carol
101, °F		1.0	e .	-	2.0		0.	70~300	Chrom 15-Alumol 7	Fluke digital thomosphere into Day that Scanger into Days	A Company of the Comp
ТхххА, dВ		0.5	8	•	* 0		1.0	105-180	Gulton microphone	R'S voltmeter info A D converter info DEAS	Popol & Kongrossor Pom callengers Standards Tob

Thompson, J. W. and Abernethy, R. B. et al. "Handbook Uncertainty in Gas Turbine Mensurements." AEDC-TR-73-5 (AD 755358), February 1973.
Assumed to be zero

TABLE 4. Continued

1				en e
	le bedra	Catalor dass	River & Recognition Pixton provided at a maximal tab.	:
	e E	Recording Device	Bell & Howell Bruch & Res g VR-5700 Analog Piston need of s asserting the project of s as a second the second the project of s as a second the project of s as a seco	
	e e	Keasuring Device	Gulton microphone	
Range		Kange	105-180	
STEADY-STATE ESTIMATED MEASURENENT* ton Index Bias Uncertainty (S) (R) + (R + 10-S)	tainty tg5S)	lo linu Paruzeok Inam	1.0	
	Uncer ±(B +	Percent to Reading		
	1as (B)	TO 11nU -aruzeaM -and	÷0	•
	es	Percent ot Reading		
		Degree or	30	
	Precision Index (S)	Init of Peasure- Juent	0.5	
	Precis	Jassag Jo Bathsag		
,	•	rarameter Designation	DYNANIC PRESSURE NEASUREMENT, dB	

. :

Thompson, J. W. and Abernethy, R. B. et al. "Handbook Uncertainty in Gas Turbine Measurements." AbDC-TR-73-5 (AD 755356), February 1973.

TABLE 4. Concluded b. Calculated parameters

Parameter Designation N P. psta Q, psta PT2, psta X, XPC, XPP, XPT X, YPC, YPP, YPT X, ZPC, ZPP, ZPT ALPHAP PHIP	STEA	DY-STA	TE ESTIM	STEADY-STATE ESTIMATED MEASUREMENT*	EXENT.		
PP, XPT PP, XPT PP, XPT PP, ZPT	Precision Index (S)		8	B1as (B)	nucer ∓(B	Uncertainty ±(B + t95S)	
W P. psta Q, psta PT2, psta Rktl0-6, ff-1 X, XPC, XPP, XPT Z, ZPC, ZPP, ZPT ALPHAP YANP PHIP	Reading Unit of Unit of	Degree of	Percent of Reading	io iin -sauzasi insm	insored to garbasa	to tinU -oruzask Inom	4/REX10-6
P, psia Q, psia PT2, psia EER10-6, ft-1 X, XPC, XPP, XPT Y, VPC, YPP, YPT Z, ZPC, ZPP, ZPT ALPHAP YANP PHIP	6.00%			0,		0.016	3/3.0
9, ps1a PT2, ps1a REX10-6, ft-1 X, XPC, XPP, XPT Z, ZPC, ZPP, ZPT ALPHAP YANP PHIP	0.0060			0.0010		0.0130	3 3.0
PT2, PS13	0.0214		,	0.0064		0.0492	3 3.0
KEX10-6, ft-1 X, XPC, XPP, XPT Y, YPC, YPP, YPT Z, ZPC, ZPP, ZPT ALPHAP YANP PHIP	0.0422	_		0.0122		0.0966	3 3.0
X, XPC, XPP, XPT Y, YPC, YPP, YPT Z, ZPC, ZPP, ZPT ALPHAP YANP PHIP	0.0655			0.1287		0.2597	3 3.0
Y, YPC, YPP, YPT Z, ZPC, ZPP, ZPT ALPHAP YAMP PHIP	0.010	L_		0.004	i i	0.024	3.3.0
Z, ZPC, ZPP, ZPT ALPHAP YANP PHIP	0.018			÷		0.036	
А.Срилр Үдвр РИЈР	0.015			0.004		0.034	
ульр Ритр	0 0.16			0.010		0.102	3.3.0
d I id	0.025	_		•		0.020	
	0.088			+0		0.176	
	•						

Abernethy, R. B. et al. and Thompson, J. W. "Handbook Uncertainty in Gas Turbine Measurements."
ARDC-FR-73-5 (AD 755356), February 1973.
Annumed to be zero

:

TABLE 5. Test Summary

M = 3, RE = $3.0 \times 10^6 ft^{-1}$, ALPHA = 0.0 deg

Configuration: Cavity Flow Model (No Probe)

STORE ¹	FENCE ²	RUN
0	0	12
0	1	11
25	0	1,20
25	1	6
50	1	16
_	_	5 ³

Configuration: Cavity Flow Model (With Probe)

		SURVE	Y STAT	ion ⁴
STORE ¹	FENCE ²	FWD	MID	AFT
0	0	15	14	13
25	σ	4	3	2
25	1	9,10	8	7
50	1	19	18	17

NOTES:

The second second

- 1. STORE Percent of cavity cross-section area occupied by store shape. Total area = 36.0 in.²
- 2. FENCE Suppression fence height normalized by estimated boundary layer thickness. δ = 0.47 in.
- 3. RUN 5 Probe calibration in free-stream. ALPHAP = -5.0 to 5.0 deg
- 4. SURVEY STATION Location of probe grid survey in inches from model leading edge.

FWD - 27.905 in. (no fence); 27.530 in. (with fence)

MID - 35.125 in.

AFT - 39.625 in.

APPENDIX III

SAMPLE TABULATED DATA

•		•	
	VOR KABBAN GAS DYNAMICS FACILITY	ARMOLD AIR FORCE STATION, TENKESSEE	AFUL CAVITY FLOW
,	,		

UATE COMPUTED 9-mOV-HI TIME COMPUTED 14:32:20 DATE RECORDED 27-OCT-HI TIME RECORDED 5:40:30 PHOJECT NUMMER V A-22

	Ž	AGE 1	GRID	1-1	٠.		-	•	· :						
	2	3 CODE	3.01	PT 18.76	539.7	3.191	6.503	PT2 6.107	PT2 T 6.107 191.9	RE 0.2916+07	01				
		CONFIG CAVITY FLOW HODEL	716 700 HOD		STOPE	FENCE 0.0	TR19.	DATA TYPE P+PH+A	TYPE		•				
		•CAVITY	-ATTITUDE-		TUKN	TURNEL CONDITIONS	TIONS		•		* POS	*PROBE*	*,	•	
	K	ALPHAC	YAVC	44		c	۵	PT2	×	>	2	ALVEAD	YAND	414	
	-	10.0	00.0	10.76	•,	3.191	0.503	6.1066	39.6234	-0.0096	0.2535	-0.0185	-0.0256	?	
•	~	10.0	0.00	18,75	•	3,189	0.503	6.1042	39,6234	-0.0041	0.3791	-0.0200	-0.0241	-0.0119	
,	~	0.01	0.00	18.75		3.189	0.503	6.1039	39,6235	9600.0-	0.5015	-0.0189	-0.0256		
	*	10.0	0.0	18.75	•	3,189	0.503	6.1042	39,6234	-0.0101	0.6285	-0.0200	-0.0270		
3	'n	0.01	00.0	18.76	•	3.191	0.503	6.1078	39.6232	-0.0041	0.7537	-0-0200	-0.0241		
l,	•	0.03	00.0	18,75	•	3.189	0.503	6.1042	39,6234	-0.0091	0.8768	-0.0196	-0.0241		
	_	0.01	0.00	18.76	•	3.191	0.503	6.1066	39,6234	-0.0100	1,0025	-0.0196	-0.0267	-0.0118	
	-	0.03	00.0	18.77	539.7	3,192	0,503	6.1089	39,6234	-0.0100	1,1265	-0.0189	-0.0285		
, 4				_											

VOW KARMAN GAS DYMANICS PACILITY Arnolu air force Station, tennessee Afwl Cavity flow	GAS DY FORCE :	NAMICS P. Station,	NCJLJTY Tennesse	Ñ						DATE COMPUTED TIME CUMPUTED DATE PECURDED TIME RECORDED
PAGE= 2	CRIO 1-		•	:				·		FROSECT NUMBER
RUN CODE N 13 6 3.01	3.01		PT TT 18.76 539.7	3.191	9.00	PT2 6.107	191.9	PT2	•	•
CAVITY FLOW HODEL	TIG HOL		STORE	75 NO.0	781P	DATA TYPE P+PW+A	TYPE +A			

9-40V-#1 14:32:20 27-0CT-#1 5:40:30

• CAVITY MODEL STATIC PRESSURES (PATINED TO P)

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1.069 1.068 890.1

070.1

DATE COMPUTED 9-NUV-81 TIME COMPUTED 14:33:20 DATE RECORDED 27-DICT-H1 TIME RECORDED 5:40:30 PROJECT NUMBER V A-22

VON KARMAN GAS OYNAMICS FACILITY ARNULU AIR FORCE STATION, TENNESSEE AFWL CAVITY FLON

C

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-	9.291E+07	
<i>:</i>	6.107 191.9	TYPE +A
	PT2 6.107	DATA TYPE P+P#+A
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	3,191	FENCE .
•	539.7	STOPE
GP10 1-1 .	19.76	•
GP 10 1	3.01	G ON MODEL
	AUN CUBE	CONFIG AVITY FLOW
PAGE 3	PUR 1.3	Š

		_	,
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POSITIONS	00000000000000000000000000000000000000		0.042 0.039 0.034 0.024 0.028 0.028 0.028
RONE POS PITOT			0.234 0.226 0.226 0.179 0.174 0.1589
• RELATIVE PROBE PITOT	444444 4444444 444444444 4444444444444		70.001 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.0000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70.0000 70000 70000 70000 70000 70000 70000 70000 70000 70000 70000 70000 7
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	33		Z-0048000

Sample 3: Cavity Acoustic and Probe Parameter Data

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